Time	Sunday, May 28 th			Monday, May 29 th			Tuesday, May 30 th		Wednesday, May 31 st			
9 ⁰⁰ - 10 ⁰⁰				PI	enary Lecture	2						
10 ⁰⁰ - 11 ⁰⁰				9 ^{3ó} - 10 ³⁰ Coffee Break 10 ³⁰ - 11 ⁰⁰		Plenary Lecture 3 10 ⁰⁰ - 11 ⁰⁰		Regular Session 15	Regular Session 16	Regular Session 17		
11 ⁰⁰ - 12 ⁰⁰			Regular Session 4 11 ⁰⁰ - 12 ³⁰ Regular Session 6 11 ⁰⁰ - 12 ³⁰ Lunch 12 ³⁰ - 14 ⁰⁰		Session 6	Coffee Break 11 ⁰⁰ - 11 ³⁰ Regular Regular Poster Session 13 Session 14 Session 14 11 ³⁰ - 13 ⁰⁰ 11 ³⁰ - 13 ⁰⁰ 11 ³⁰ - 13 ⁰⁰			10 ⁰⁰ - 11 ³⁰ 10 ⁰⁰ - 11 ³⁰ 10 ⁰⁰ - 11 ³⁰ Closing Ceremony 11 ³⁰ - 11 ⁴⁵		10 ⁰⁰ - 11 ³⁰ 30 - 11 ⁴⁵	
12 ⁰⁰ - 13 ⁰⁰					11 - 12 -			Session 11 ³⁰ - 13 ⁰⁰	Lunch 12⁰⁰ - 13³⁰			
13 ⁰⁰ - 14 ⁰⁰					Lunch 13 ⁰⁰ - 14 ³⁰							
14 ⁰⁰ - 15 ⁰⁰	Opening Ceremony 14⁴⁵ - 15⁰⁰				Regular							
15 ⁰⁰ - 16 ⁰⁰	Plenary Lecture 1 15 ⁰⁰ - 16 ⁰⁰				Session 9 14 ³⁰ - 16 ⁰⁰							
16 ⁰⁰ - 17 ⁰⁰	Coffee Break 16⁰⁰ - 16³⁰		Coffee Break 16 ⁰⁰ - 16 ³⁰									
17 ⁰⁰ - 18 ⁰⁰		Regular Session 2 16 ³⁰ - 18 ⁰⁰	Regular Session 3 16 ³⁰ - 18 ⁰⁰	Regular Session 10 16 ³⁰ - 18 ⁰⁰	Regular Session 11 16 ³⁰ - 18 ⁰⁰	Regular Session 12 16 ³⁰ - 18 ⁰⁰		ptional Progra Castle / Peleș 15 ⁰⁰ - 20 ⁰⁰				
18 ⁰⁰ - 19 ⁰⁰												
19 ⁰⁰ - 20 ⁰⁰				Social Event 19⁰⁰ -								
20 ⁰⁰ -	Welcome Party 19³⁰ -					Dinner 20⁰⁰ -						

Conference Program

Sunday, May 28th, 2017

13 ³⁰ - 18 ⁰⁰	Registration
14 ⁴⁵ - 15 ⁰⁰	Opening Ceremony (George Enescu Hall)
15 ⁰⁰ - 16 ⁰⁰	Plenary Lecture 1 - Sliding modes in continuous and discrete time domains (George Enescu Hall)
16 ⁰⁰ - 16 ³⁰	Coffee Break
16 ³⁰ - 18 ⁰⁰	Regular Session 1 – Theory and application of control systems (George Enescu Hall)
16 ³⁰ - 18 ⁰⁰	Regular Session 2 – Automation, mechatronics, robotics (Nicolae Iorga Hall)
16 ³⁰ - 18 ⁰⁰	Regular Session 3 – Intelligent embedded systems, instrumentation and Internet of things (IoT) (Mihai Eminescu Hall)

Welcome Party

19³⁰ -

Monday, May 29th, 2017		
9 ⁰⁰ - 18 ⁰⁰	Registration	
9 ³⁰ - 10 ³⁰	Plenary Lecture 2 - On the Use of Feedback Controllers for Stock Trading (George Enescu Hall)	
10 ³⁰ - 11 ⁰⁰	Coffee Break	
11 ⁰⁰ - 12 ³⁰	Regular Session 4 – Theory and application of control systems (George Enescu Hall)	
11 ⁰⁰ - 12 ³⁰	Regular Session 5 – Automation, mechatronics, robotics (Nicolae Iorga Hall)	
11 ⁰⁰ - 12 ³⁰	Regular Session 6 – Measurement, sensors, monitoring and diagnostic systems (Mihai Eminescu Hall)	
12^{30} - 14^{00}	Lunch	

$14^{30} - 16^{00}$	Regular Session 7 – Theory and application of control systems (George Enescu Hall)
$14^{30} - 16^{00}$	Regular Session 8 – Automation, mechatronics, robotics (Nicolae Iorga Hall)
$14^{30} - 16^{00}$	Regular Session 9 – (Mihai Eminescu Hall)
16 ⁰⁰ - 16 ³⁰	Coffee Break
16 ³⁰ - 18 ⁰⁰	Regular Session 10 – Software Tools and Methods (George Enescu Hall)
16 ³⁰ - 18 ⁰⁰	Regular Session 11 – Automation, mechatronics, robotics (Nicolae Iorga Hall)
16 ³⁰ - 18 ⁰⁰	Regular Session 12 – Measurement, sensors, monitoring and diagnostic systems (Mihai Eminescu Hall)
19 ⁰⁰ -	Social Event

Tuesday, May 30th, 2017

9 ⁰⁰ - 13 ⁰⁰	Registration
10 ⁰⁰ - 11 ⁰⁰	Plenary Lecture 3 - PID tuning: design tradeoffs and unified perspectives (George Enescu Hall)
11 ⁰⁰ - 11 ³⁰	Coffee Break
11 ³⁰ - 13 ⁰⁰	Regular Session 13 – Engineering application of informatics (George Enescu Hall)
11 ³⁰ - 13 ⁰⁰	Regular Session 14 – Identification, modeling, simulation of processes and systems (Nicolae Iorga Hall)
11 ³⁰ - 13 ⁰⁰	Poster Session (Mihai Eminescu Hall)
13 ⁰⁰ - 14 ³⁰	Lunch
15 ⁰⁰ - 20 ⁰⁰	Optional Program – Bran Castle / Peleş Castle
20 ⁰⁰ -	Dinner

Wednesday, May 31st, 2017

10 ⁰⁰ - 11 ³⁰	Regular Session 15 – Identification, modeling, simulation of processes and systems (George Enescu Hall)
10 ⁰⁰ - 11 ³⁰	Regular Session 16 – Engineering education in control and computer systems (Nicolae Iorga Hall)
10 ⁰⁰ - 11 ³⁰	Regular Session 17 – Measurement, sensors, monitoring and diagnostic systems (Mihai Eminescu Hall)
$11^{30} - 11^{45}$	Closing Ceremony (George Enescu Hall)
12 ⁰⁰ - 13 ³⁰	Lunch

Sunday, May 28th, 2017

Opening Ceremony

14⁴⁵ - 15⁰⁰ – George Enescu Hall Chairmen: Dan POPESCU, Radim FARANA, Karol KOSTÚR, Bogdan SAPIŃSKI, József VÁSÁRHELYI

Plenary Lecture 1 - Sliding modes in continuous and discrete time domains

Prof. Andrzej BARTOSZEWICZ, Technical University of Lodz

15⁰⁰ - 16⁰⁰ - George Enescu Hall Chairman: Vladimir RĂSVAN

Regular Session 1 - Theory and application of control systems

16³⁰ – 18⁰⁰ – George Enescu Hall Chairman: Vladimir RĂSVAN Co-chairman: Sergiu CARAMAN

16³⁰ - 16⁴⁵ Hana **VAŠKOVÁ** and Karel **KOLOMAZNÍK** – *Mathematical model of expenses for collagen hydrolyzate production*

16⁴⁵ - 17⁰⁰ Mihaela **SBARCIOG**, George **IFRIM**, Sergiu **CARAMAN** and Alain Vande **WOUWER** – *Multivariable Predictive Control of a Photobioreactor System*

- 17⁰⁰ 17¹⁵ Joanna **ZIETKIEWICZ** and Adam **OWCZARKOWSKI** Direct Nonlinear Model Predictive Control and Predictive Control with Feedback Linearization. A Comparison of Approaches
- 17¹⁵ 17³⁰ Vladimir **RĂSVAN**, Daniela **DANCIU** and Dan **POPESCU** *On Huygens synchronization. Application to Van der Pol oscillators with distributed couplings*

Regular Session 2 - Automation, mechatronics, robotics

16³⁰ – 18⁰⁰ – Nicolae Iorga Hall Chairman: Josef CERNOHORSKY Co-chairman: Frank E. SCHNEIDER

- 16³⁰ 16⁴⁵ Martin **VOJÍŘ**, Leoš **BERAN** and Václav **ZÁDA** *Mobile Robot Concept with Walking Wheels Made of Rotary Segments*
- Frank E. **SCHNEIDER** and Dennis **WILDERMUTH** Using Robots for Firefighters and First Responders Scenario Specification and Exemplary System Description
- 17⁰⁰ 17¹⁵ Josef **CERNOHORSKY**, Ondrej **MACH** and Pavel **JANDURA** *Mobile robot localization and object description*
- 17¹⁵ 17³⁰ Jan ČEJKA and Josef CERNOHORSKY Inverse Kinematic Problem Solved By New Heuristic Algorithm Length Relaxation Method

Regular Session 3 – Intelligent embedded systems, instrumentation and Internet of things (IoT)

16³⁰ – 18⁰⁰ – Mihai Eminescu Hall Chairman: József VÁSÁRHELYI Co-chairman: Tomas ZITTA

- 16³⁰ 16⁴⁵ Aleksejs **ZACEPINS**, Aldis **PECKA**, Vitalijs **OSADCUKS** and Armands **KVIESIS** Development of Internet of Things concept for Precision Beekeeping
- 16⁴⁵ 17⁰⁰ Simona Vasilica **OPREA**, Adela **BARA** and Marinela **MIRCEA** *Data acquisition solutions for electricity consumer with connected to smart grids*

- 17⁰⁰ 17¹⁵ Ahmed **BOUZID** and József **VÁSÁRHELYI** Implementation of Dead Reckoning Solution on Zynq Target
- 17¹⁵ 17³⁰ Jakub **KOLARIK** and Zdenek **SLANINA** *Fuzzy Control Application in Swarm Robotic Cars*
- 17³⁰ 17⁴⁵ Tomas **ZITTA**, Marek **NERUDA** and Lukas **VOJTECH** *The Security of RFID Readers with IDS/IPS Solution Using Raspberry Pi*
- Nicolae **PĂTRĂȘCOIU**, Rus **COSMIN** and Ioana Camelia **BARBU** Virtual instrumentation for data acquisition and remote control

Monday, May 29th, 2017

Plenary Lecture 2 - On the Use of Feedback Controllers for Stock Trading

Prof. B. Ross BARMISH, University of Wisconsin, Madison 9^{30} - 10^{30} – George Enescu Hall

Chairman: Dan POPESCU

Regular Session 4 - Theory and application of control systems

11⁰⁰ – 12³⁰ – George Enescu Hall Chairman: Renata WAGNEROVÁ Co-chairman: Piotr LEŚNIEWSKI

- 11⁰⁰ 11¹⁵ Mihai **LUNGU** and Romulus **LUNGU** *The Control of Airplane Landing in Longitudinal and Lateral-directional Planes by using the H-inf Control*
- 11¹⁵ 11³⁰ Mihai **LUNGU** and Romulus **LUNGU** Complete Landing Autopilot having Control Laws Based on Neural Networks and Dynamic Inversion
- 11 30 11 45 Jan **GEBAUER** and Renata **WAGNEROVÁ** Enhanced UAV Propulsion System.
- 11⁴⁵ 12⁰⁰ Piotr **LEŚNIEWSKI** Sliding mode control with time-varying sliding hyperplanes: a survey

- 12⁰⁰ 12¹⁵ Marian **BARBU**, Ramon **VILANOVA**, Ignacio **SANTIN** and Montse **MENESES** Decentralized Control Strategies Evaluation On an Integrated Urban Wastewater System
- 12¹⁵ 12³⁰ Karla **SLADKÁ** and Miroslav **MAHDAL** *Behaviour of 2DOF* Controller in the Closed-loop Control with Pneumatic Actuator

Regular Session 5 - Automation, mechatronics, robotics

11⁰⁰ – 12³⁰ – Nicolae Iorga Hall Chairman: Dorin POPESCU Co-chairman: Tomáš KOT

- 11⁰⁰ 11¹⁵ Florin Daniel **ANTON** and Silvia **ANTON** Trajectory Generation for Robot Engraving and Milling Tasks
- 11¹⁵ 11³⁰ Radu Gheorghe **CHETAN**, Roxana **BOTH-RUSU**, Eva-Henrietta **DULF** and Clement **FESTILA** – *Physical Model of a Quarter-car Active Suspension System*
- Dorin **POPESCU**, Florin **MANTA**, Ligia **RUSU**, Taina-Elena **AVRAMESCU**, Mihaela **ZĂVĂLEANU** and Anca **PETRIȘOR** Medical and technical requirements analysis for upper limb rehabilitation system
- 11⁴⁵ 12⁰⁰ Tomáš **KOT**, Babjak **JAN** and Petr **NOVÁK** Analysis and Prevention of Selected Risks of Remotely and Autonomously Controlled Mobile Robot TeleRescuer
- 12⁰⁰ 12¹⁵ Tomáš **KOT**, Milan **MIHOLA**, Jan **BABJAK** and Petr **NOVÁK** *Gripper with Precisely Adjustable Gripping Force*
- 12¹⁵ 12³⁰ Roland **BARTÓK** and József **VÁSÁRHELYI** Two Methods for Autonomous Robot Obstacle Sensing and Application Programming Interface for Fuzzy Rule Interpolation

Regular Session 6 - Measurement, sensors, monitoring and diagnostic systems

11⁰⁰ – 12³⁰ – Mihai Eminescu Hall Chairman: Jiří KULHÁNEK Co-chairman: Honoriu VĂLEAN

- Vladimír **ZBOŽÍNEK**, Petr **TOMČÍK**, Jiří **KULHÁNEK**, Petr **FOJTÍK**, Michal **BURÁŇ** and Miroslav **SUCHÁNEK** Car Axle Testing on Hydropulse
- 11¹⁵ 11³⁰ Jiří **KULHÁNEK** and Jaromír **ŠKUTA** Calibration of MEMs accelerometer with digital output
- 11³⁰ 11⁴⁵ Martin **DIBLÍK**, Jan **PODRAPSKÝ** and Leoš **BERAN** *On The Accuracy Of Indirect Torque Measurement Using Frequency Converter*
- Vlastimil **ŠETKA**, Roman **ČEČIL** and Miloš **SCHLEGEL** *Triple Inverted Pendulum System Implementation Using a New ARM/FPGA Control Platform*
- 12⁰⁰ 12¹⁵ Adela **PUȘCAȘIU**, Silviu **FOLEA**, Honoriu **VĂLEAN**, Alexandra **FANCA** and Teodora **SANISLAV** Monitoring the on-site contribution to the greenhouse effect by distributed measurement of carbon dioxide
- 12¹⁵ 12³⁰ Pavel **TRNKA**, Milan **HOFREITER** and Jan **SOVA** Combination of Techniques for the Fault Diagnostics

Regular Session 7 - Theory and application of control systems

14³⁰ – 16⁰⁰ – George Enescu Hall Chairman: Paolo MERCORELLI Co-chairman: Farshad KHORRAMI

- 14³⁰ 14⁴⁵ Paolo **MERCORELLI** Combining Flatness Based Feedforward Action with a Fractional PI Regulator to Control the Intake Valve Engine
- 14⁴⁵ 15⁰⁰ Paolo **MERCORELLI** A Geometric Approach for the Design and Control of an Electromagnetic Actuator to Minimise Vibrations and Disturbances

- 15⁰⁰ 15¹⁵ Prashanth **KRISHNAMURTHY** and Farshad **KHORRAMI** Global Output-Feedback Control for Strict-Feedback-Like Systems with Time-Delayed Input Unmodeled Dynamics
- 15¹⁵ 15³⁰ Martin **JURÁNEK**, Petr **TOMČÍK** and Jiří **KULHÁNEK** *The* anti slip control system on electric car independent axle
- 15³⁰ 15⁴⁵ Mohammad **TABATABAEI** CRA based control of incommensurate fractional order systems
- 15⁴⁵ 16⁰⁰ Altuğ **İFTAR** Decentralized Robust Control of Infinitedimensional Systems

Regular Session 8 - Automation, mechatronics, robotics

14³⁰ – 16⁰⁰ – Nicolae Iorga Hall Chairman: Bogdan SAPIŃSKI Co-chairman: Janusz GOLDASZ

- 14³⁰ 14⁴⁵ Agata **NAWROCKA**, Marcin **NAWROCKI** and Andrzej **KOT** *Advanced control algorithms for mobile robot*
- 14⁴⁵ 15⁰⁰ Łukasz **JASTRZĘBSKI** and Bogdan **SAPIŃSKI** Electrical Interface For An MR Damper-based Vibration Reduction System With Energy Harvesting Capability
- 15^{00} 15^{15} Václav **ZÁDA** Exponentially Stable Tracking Control in Terms of Hamiltonian Mechanics
- 15¹⁵ 15³⁰ Janusz **GOLDASZ** Study of a Modular Magnetorheological Valve
- 15³⁰ 15⁴⁵ Nguyen Van Dong **HAI**, Mircea **IVĂNESCU** and Mircea **NIȚULESCU**. Controller based on Lyapunov for a Class of Running Robot
- 15⁴⁵ 16⁰⁰ Martin **GOUBEJ**, Tomáš **POPULE** and Alois **KREJČÍ** *Friction Compensation in Mechatronic Systems*

Regular Session 9 - Theory and application of control systems

14³⁰ – 16⁰⁰ – Mihai Eminescu Hall Chairman: Mathaus Ferreira Da SILVA Co-chairman: Miroslav PAWLENKA

- Vinícius Ferreira **VIDAL**, Leonardo De Mello **HONÓRIO**, Murillo Ferreira Dos **SANTOS**, Mathaus Ferreira Da **SILVA**, Augusto Santiago **CERQUEIRA** and Edmar José De **OLIVEIRA** – *UAV Vision Aided Positioning System for Location* and Landing
- Mathaus Ferreira Da **SILVA**, Augusto Santiago **CERQUEIRA**, Vinícius Ferreira **VIDAL**, Leonardo De Mello **HONÓRIO** and Murillo Ferreira Dos **SANTOS** Landing Area Recognition by Image Applied to an Autonomous Control Landing of VTOL Aircraft
- 15⁰⁰ 15¹⁵ João Marcos Simões **RIBEIRO**, Murillo Ferreira Dos **SANTOS**, Marlon José Do **CARMO** and Mathaus Ferreira Da **SILVA** – Comparison of PID Controller Tuning Methods: Classical Techniques versus Optimization Algorithms
- Murillo Ferreira Dos **SANTOS**, Vinícius Silva **PEREIRA**, André Cruz **RIBEIRO**, Mathaus Ferreira Da **SILVA**, Marlon José Do **CARMO**, Vinícius Ferreira **VIDAL**, Leonardo De Mello **HONÓRIO**, Augusto Santiago **CERQUEIRA** and Edmar José De **OLIVEIRA** Simulation and Comparison Between a Linear and Non-linear Technique Applied to Altitude Control in Quadcopters
- 15³⁰ 15⁴⁵ Jiří TŮMA, Pavel ŠURÁNEK, Jaroslav LOS and Miroslav MAHDAL Simulation study of using a cascade of all-pass filters for active vibration control of mechanical structures
- 15⁴⁵ 16⁰⁰ Miroslav **PAWLENKA** and Miroslav **MAHDAL** *Automatically Tunable Bandpass Filter*

Regular Session 10 - Software Tools and Methods

16³⁰ – 18⁰⁰ – George Enescu Hall Chairman: Mihai MOCANU

Co-chairman: Marius BREZOVAN

- 16³⁰ 16⁴⁵ Călin **CONSTANTINOV**, Nicoleta-Florina **BĂRBULESCU**, Mihai **MOCANU**, Elvira **POPESCU** and Andrei **MOCANU** MovieRate: Considerations on applying a custom social reputation engine for movie reviews
- 16⁴⁵ 17⁰⁰ Faiq **BAJI** and Mihai **MOCANU** Connected components Objects Feature for CBIR
- 17⁰⁰ 17¹⁵ Brice Evrard **TAREHY**, Thomas **MAHATODY**, Josvah Paul **RAZAFIMANDIMBY** and Jean Luc **RAZAFINDRAMINTSA** Reuse environment based on elaborate Lexicon Extend Language
- 17¹⁵ 17³⁰ Bogdan **POPA** Study about the edge detection algorithm and its applications
- 17³⁰ 17⁴⁵ Teodora **SANISLAV** and George **MOIS** A Dependability Analysis Model in the Context of Cyber-Physical Systems
- 17⁴⁵ 18⁰⁰ Eugen **GANEA**, Ionuț **RESCEANU** and Nicu George **BÎZDOACĂ** Haptic Devices Synchronization into a Software Simulator

Regular Session 11 - Automation, mechatronics, robotics

16³⁰ – 18⁰⁰ – Nicolae Iorga Hall Chairman: Radim FARANA Co-chairman: Radek ŠTOHL

- 16³⁰ 16⁴⁵ Ivo **FORMÁNEK** and Radim **FARANA** Design and Synthesis of Control Systems of Material Flow in Industrial Companies
- 16⁴⁵ 17⁰⁰ Ivo **FORMÁNEK** and Radim **FARANA** Experimental Identification of Mechanical Properties of Variable Speed Drives
- 17⁰⁰ 17¹⁵ Radek **ŠTOHL** and Karel **STIBOR** *The CIP Safety Protocol in Connecting Single Machines to Create Production Lines*

- 17¹⁵ 17³⁰ Ata Jahangir **MOSHAYEDI** and D.C **GHARPURE** Evaluation Of Bio Inspired Mokhtar: Odor Localization System
- 17³⁰ 17⁴⁵ Jan **DEDEK**, Matej **GOLEMBIOVSKY** and Zdenek **SLANINA** Sensoric system for navigation of SWARM robotics platform
- 17⁴⁵ 18⁰⁰ Tomas **DOCEKAL** and Zdenek **SLANINA** Control system based on FreeRTOS for data acquisition and distribution on SWARM robotics platform

Regular Session 12 - Measurement, sensors, monitoring and diagnostic systems

 $16^{30} - 18^{00}$ – Mihai Eminescu Hall

Chairman: János VÉGH

Co-chairman: Liviu MICLEA

- 16³⁰ 16⁴⁵ Péter **MOLNÁR** and János **VÉGH** Measuring performance of processor instructions and operating system services in soft processor based systems
- 16⁴⁵ 17⁰⁰ János **VÉGH** and Péter **MOLNÁR** *How to measure perfectness of parallelization in hardware/software systems*
- 17⁰⁰ 17¹⁵ Pavel **TOMASEK** Estimation of Permittivity of Materials using Sub-Millimeter Waves
- 17¹⁵ 17³⁰ Dušan **KROKAVEC**, Anna **FILASOVÁ** and Tibor **KOČÍK** *Proportional-Difference Observers in Additive Fault Estimation*
- 17³⁰ 17⁴⁵ Radana **KAHANKOVA**, Radek **MARTINEK** and Petr **BILIK** Fetal ECG Extraction from Abdominal ECG Using RLS based Adaptive Algorithms
- 17⁴⁵ 18⁰⁰ Bianca **ZAHARIE**, Liviu **MICLEA**, Gökçe **IŞLAK** and Cătălin **DEHELEAN** A Hierarchical Approach of Order Acceptance and Delivery Date Setting Problems in the Apparel Industry

Tuesday, May 30th, 2017

Plenary Lecture 3 - PID tuning: design tradeoffs and unified perspectives

Prof. Ramon VILANOVA, Universitat Autonoma de Barcelona

10⁰⁰ - 11⁰⁰ – George Enescu Hall Chairman: Dan SELISTEANU

Regular Session 13 - Engineering application of informatics

11³⁰ – 13⁰⁰ – George Enescu Hall Chairman: Stanislav PALÚCH Co-chairman: Judit Mária PINTÉR

11³⁰ - 11⁴⁵ Stanislav **PALÚCH** and Tomáš **MAJER** – Efective and Fast Implementation of k-shortest paths algorithms

11⁴⁵ - 12⁰⁰ Štefan **PEŠKO** and Tomáš **MAJER** – Inverse Optimization for Bus Scheduling Problems

12⁰⁰ - 12¹⁵ Tomáš **MAJER**, Stanislav **PALÚCH** and Štefan **PEŠKO** – Algorithms for Vehicle and Crew Scheduling in Regular Bus Transport

12¹⁵ - 12³⁰ Jiří **CZEBE** and Jaromír **ŠKUTA** – *Usage of single-chip computers for control MIMO systems*

12³⁰ - 12⁴⁵ László **CZAP**, Judit Mária **PINTÉR** and Attila K. **VARGA** – Segmentation the Speech of Hard of Hearing Children

12⁴⁵ - 13⁰⁰ Răzvan **MOCANU** and Alexandru **ONEA** – Robust Optimal Control of Externally Excited Synchronous Machine Based on Passivity Theory

Regular Session 14 - Identification, modeling, simulation of processes and systems

11³⁰ – 13⁰⁰ – Nicolae Iorga Hall Chairman: Karol KOSTUR Co-chairman: Huseyin AKCAY

11³⁰ - 11⁴⁵ Alexandru-Nicolae **TUDOSIE** – Hydro-Mechanical Fuel Flow Controller for Aircraft Jet Engines

- 12⁰⁰ 12¹⁵ Jiří **HOLÍK**, Michal **DORDA**, Vojtěch **GRAF** and Dušan **TEICHMANN** Roundabout capacity analysis based on cloud simulation in Witness
- 12¹⁵ 12³⁰ Huseyin **AKCAY** and Semiha **TURKAY** Parallel Track Models from Road Measurements
- Vlad MUREŞAN, Mihail ABRUDEAN, Honoriu VĂLEAN, Iulia CLITAN, Mihaela-Ligia UNGUREŞAN, Tiberiu COLOŞI, Diana SAS, Adela PUŞCAŞIU, Alexandra FANCA Pipes Temperature Control in an Annealing Furnace
- 12⁴⁵ 13⁰⁰ Karol **KOSTUR**. *Mathematical model for optimisation of a thickness of furnace lining*

Poster Session

11³⁰ – 13⁰⁰ – Mihai Eminescu Hall Chairman: Monica ROMAN Co-chairman: Marius MARIAN

Elena **DRABIKOVÁ**, Erika **FECKOVÁ SKRABUL'ÁKOVÁ**– *Decision Trees - a Powerful Tool in Mathematical and Economic Modeling*

Diana RÁŠKAYOVÁ, Marek LACIAK, Tawfik MUDARRI – The System of Optimization Quantity of Oxidizers in UCG Process with Thermodynamic Model

Miluse VITECKOVA, Antonin VITECEK, Karla SLADKA— Controller Tuning by Desired Model Method

Matej **LUKAC**, Jan **TERPAK**, Pavel **HOROVCAK** – The Modelling of Processes in the Area of the Raw Material Processing using Service Oriented Architecture

Ján KAČUR, Marek LACIAK, Milan DURDÁN, Patrik FLEGNER— Utilization of Machine Learning Method in Prediction of UCG Data

Jan **TERPAK**, Pavel **HOROVCAK**, Matej **LUKAC**– Numerical Solution for Time Fractional-Order Diffusion-Wave Equation Using Explicit Finite Difference Method in Web Service Form

Přemysl **STRAKOŠ**, Jiří **TŮMA** – Mathematical Modelling and Controller Design of Inverted Pendulum

Radim **HÝL**, Renata **WAGNEROVÁ** – Fast development of controllers with Simulink Coder

Marius MARIAN, Florin STÎNGĂ, Valentin KESE and Lucian BĂRBULESCU – A case study in real-time implementations of a predictive control algorithm

Piotr **SULIGA** and Andrzej **SIOMA** – Surface structure reconstruction using a multispectral variable angle light source

Dorina **PURCARU**, Anca **PURCARU** and Virginia **RĂDULESCU** – Temperature Measurement and Control System for Engineering Education

Dorina **PURCARU**, Anca **PURCARU** and Ioan Mircea **GORDAN** – Study, Testing and Application of Proximity Sensors for Experimental Training on Measurement Systems

Wednesday, May 31st, 2017

Regular Session 15 - Identification, modeling, simulation of processes and systems

 $10^{00} - 11^{30}$ – George Enescu Hall

Chairman: Emil PETRE

Co-chairman: Dorin ŞENDRESCU

- 10⁰⁰ 10¹⁵ Constantin MARIN, Dan POPESCU, Emil PETRE and Monica ROMAN Mathematical modelling of belt drying plants with several temperature zones
- 10¹⁵ 10³⁰ Emil **PETRE**, Dan **SELIȘTEANU**, Dorin **ȘENDRESCU**, Marian **BARBU** and Sergiu **CARAMAN** An Adaptive Control Structure for an Anaerobic Digestion Process with Unknown Inputs

- 10³⁰ 10⁴⁵ Radu-Lucian **CONSTANTINESCU**, Monica **ROMAN** and Dan **SELIȘTEANU** Simplified numerical methods used for the approximations of chaotic solutions of dynamical systems
- 10⁴⁵ 11⁰⁰ Marius **BREZOVAN** and Liana **STĂNESCU** Using High-Level Petri Nets with Object-Orientation for Modeling Flexible Manufacturing Systems
- 11⁰⁰ 11¹⁵ Dorin **ŞENDRESCU**, Emil **PETRE** and Dan **SELIŞTEANU** Nonlinear PID Controller for a Bacterial Growth Bioprocess
- 11¹⁵ 11³⁰ Florin Andrei **RUSU** and Gheorghe **LIVINT** $H\infty$ Controller for power sources applied to electrical vehicles

Regular Session 16 - Engineering education in control and computer systems

10⁰⁰ – 11³⁰ – Nicolae Iorga Hall Chairman: Marco TEMPERINI Co-chairman: Elvira POPESCU

- 10⁰⁰ 10¹⁵ Cristian **MIHĂESCU**, Oana Maria **TEODORESCU**, Paul Ștefan **POPESCU** and Mihai **MOCANU** Learning Analytics Solution for Building Personalized Quiz Sessions
- 10¹⁵ 10³⁰ Alex **BECHERU** and Elvira **POPESCU** Design of a Conceptual Knowledge Extraction Framework for a Social Learning Environment based on Social Network Analysis Methods
- 10³⁰ 10⁴⁵ Sabin **SIMIONESCU**, Dana **ŠUNÍKOVÁ** and Zuzana **KUBINCOVÁ** Gamification of peer-assessment in learning management system
- Paolo **DI GIAMBERARDINO** and Marco **TEMPERINI** Adaptive access to robotic learning experiences in a remote laboratory setting

Regular Session 17 - Measurement, sensors, monitoring and diagnostic systems

 $10^{00} - 11^{30}$ – Mihai Eminescu Hall

Chairman: Ciprian LUPU

Co-chairman: Marian POPESCU

- 10⁰⁰ 10¹⁵ Dan **SECUIANU**, Cosmin **MIHAI**, Andrei **VULPE** and Ciprian **LUPU** *Implementation of an autonomous mobile platform based on computer vision*
- 10¹⁵ 10³⁰ Lavinius Ioan **GLIGA**, Ciprian **LUPU**, Houcine **CHAFOUK** and Dumitru **POPESCU** Innovations in Fault Detection and Tolerant Control for a Wind Farm, using Wireless Sensor Networks
- 10³⁰ 10⁴⁵ Ciprian **LUPU**, Cosmin **MIHAI**, Dan **SECUIANU** and Andrei **VULPE** Improvement precision for fault detection system in fluids transfer infrastructures
- 10⁴⁵ 11⁰⁰ Jan **WEGEHAUPT** and Dariusz **BUCHCZIK** Moisture measurement of bulk materials in an electromagnetic mill
- 11⁰⁰ 11¹⁵ Bogdan **POPA** and Marian **POPESCU**. The analysis parameters for the A.C. engine for actuating of a grinding wheat system
- 11¹⁵ 11³⁰ Mircea Catalin **CONSTANTINESCU**, Lucian **GRUIONU** and Cătălin **CERBULESCU** Low cost and easy to use programmable driver for DC micromotors used in high precision multi axis motion system

Closing Ceremony

11³⁰ – 11⁴⁵ – George Enescu Hall

Chairmen: Dan POPESCU, Radim FARANA, Karol KOSTÚR, Bogdan

SAPIŃSKI, József VÁSÁRHELYI